Adafruitfeatherwing Library Documentation

Release 1.0

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Contents

This library provides FeatherWing specific classes for those that require a significant amount of initialization.

CHAPTER 1

Dependencies

These drivers depends on:

- Adafruit CircuitPython
- INA219
- Seesaw
- HT16K33

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the Adafruit library and driver bundle and highly recommended over installing each one.

1.1 Installing from PyPI

On supported GNU/Linux systems like the Raspberry Pi, you can install the driver locally from PyPI. To install for current user:

```
pip3 install adafruit-circuitpython-featherwing
```

To install system-wide (this may be required in some cases):

```
sudo pip3 install adafruit-circuitpython-featherwing
```

To install in a virtual environment in your current project:

```
mkdir project-name && cd project-name
python3 -m venv .env
source .env/bin/activate
pip3 install adafruit-circuitpython-featherwing
```

CHAPTER 2

Contributing

Contributions are welcome! Please read our Code of Conduct before contributing to help this project stay welcoming.

CHAPTER 3

Building locally

To build this library locally you'll need to install the circuitpython-build-tools package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-featherwing --
↪library_location .
```

3.1 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the index.html in your browser to view them. It will also (due to -W) error out on any warning like Travis will. This is a good way to locally verify it will pass.

CHAPTER 4

Table of Contents

4.1 Simple tests

Ensure your device works with this simple test.

Listing 1: examples/featherwing_ina219_simpletest.py

```
""" Example to print out the voltage and current using the INA219 """
import time
from adafruit_featherwing import ina219_featherwing

INA219 = ina219_featherwing.INA219FeatherWing()

while True:
    print("Bus Voltage:   {} V".format(INA219.bus_voltage))
    print("Shunt Voltage: {} V".format(INA219.shunt_voltage))
    print("Voltage:       {} V".format(INA219.voltage))
    print("Current:       {} mA".format(INA219.current))
    print("")
    time.sleep(0.5)
```

Listing 2: examples/featherwing_joy_simpletest.py

```
"""This example zeros the joystick, and prints when the joystick moves
   or the buttons are pressed."""
import time
from adafruit_featherwing import joy_featherwing

wing = joy_featherwing.JoyFeatherWing()
last_x = 0
last_y = 0

while True:
    x, y = wing.joystick
```

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```
    if (abs(x - last_x) > 3) or (abs(y - last_y) > 3):
        last_x = x
        last_y = y
        print(x, y)
    if wing.button_a:
        print("Button A!")
    if wing.button_b:
        print("Button B!")
    if wing.button_x:
        print("Button X!")
    if wing.button_y:
        print("Button Y!")
    if wing.button_select:
        print("Button SELECT!")
    time.sleep(.01)
```

Listing 3: examples/featherwing_alphanum_simpletest.py

```
"""This example changes the fill, brightness, blink rates,
shows number and text printing, displays a counter
and then shows off the new marquee features."""

from time import sleep
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()

#Fill and empty all segments
for count in range(0, 3):
    display.fill(True)
    sleep(0.5)
    display.fill(False)
    sleep(0.5)

#Display a number and text
display.print(1234)
sleep(1)
display.print('Text')

#Change brightness
for brightness in range(0, 16):
    display.brightness = brightness
    sleep(0.1)

#Change blink rate
for blink_rate in range(3, 0, -1):
    display.blink_rate = blink_rate
    sleep(4)
display.blink_rate = 0

#Show a counter using decimals
count = 975.0
while count < 1025:
    count += 1
    display.print(count)
    sleep(0.1)
```

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```
39
40 #Show the Marquee
41 display.marquee('This is a really long message!!!  ', 0.2)
```

4.2 adafruit_featherwing.ina219_featherwing

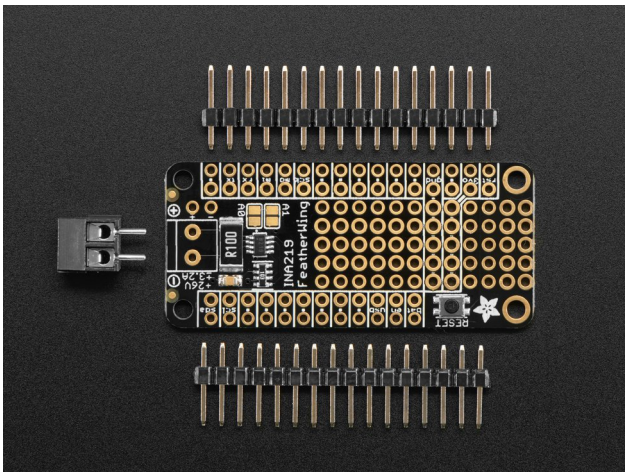
Helper for using the INA219 FeatherWing.

- Author(s): Kattni Rembor

class adafruit_featherwing.ina219_featherwing.**INA219FeatherWing**
Class representing an Adafruit INA219 FeatherWing.

Automatically uses the feather's I2C bus.

bus_voltage
Bus voltage returns volts.



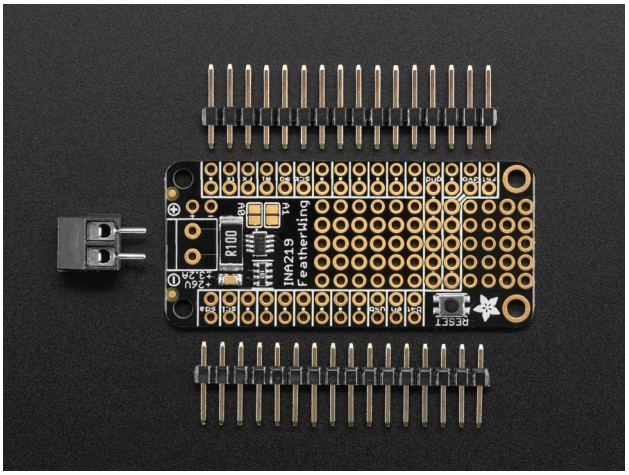
This example prints the bus voltage with the appropriate units.

```
from adafruit_featherwing import ina219_featherwing
import time

ina219 = ina219_featherwing.INA219FeatherWing()

while True:
    print("Bus Voltage: {} V".format(ina219.bus_voltage))
    time.sleep(0.5)
```

current
Current returns mA.



This example prints the current with the appropriate units.

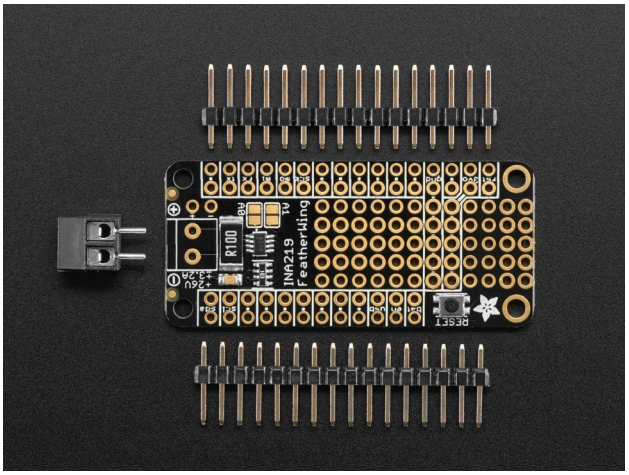
```
from adafruit_featherwing import ina219_featherwing
import time

ina219 = ina219_featherwing.INA219FeatherWing()

while True:
    print("Current: {} mA".format(ina219.current))
    time.sleep(0.5)
```

shunt_voltage

Shunt voltage returns volts.



This example prints the shunt voltage with the appropriate units.

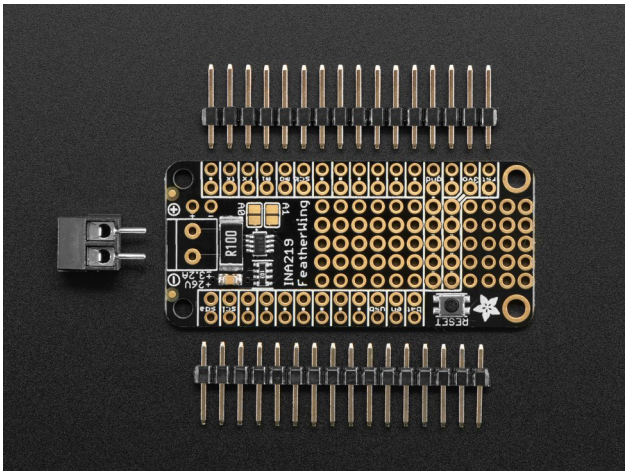
```
from adafruit_featherwing import ina219_featherwing
import time

ina219 = ina219_featherwing.INA219FeatherWing()

while True:
    print("Shunt Voltage: {} V".format(ina219.shunt_voltage))
    time.sleep(0.5)
```

voltage

Voltage, known as load voltage, is bus voltage plus shunt voltage. Returns volts.



This example prints the voltage with the appropriate units.

```
from adafruit_featherwing import ina219_featherwing
import time

ina219 = ina219_featherwing.INA219FeatherWing()

while True:
    print("Voltage: {} V".format(ina219.voltage))
    time.sleep(0.5)
```

4.3 adafruit_featherwing.joy_featherwing

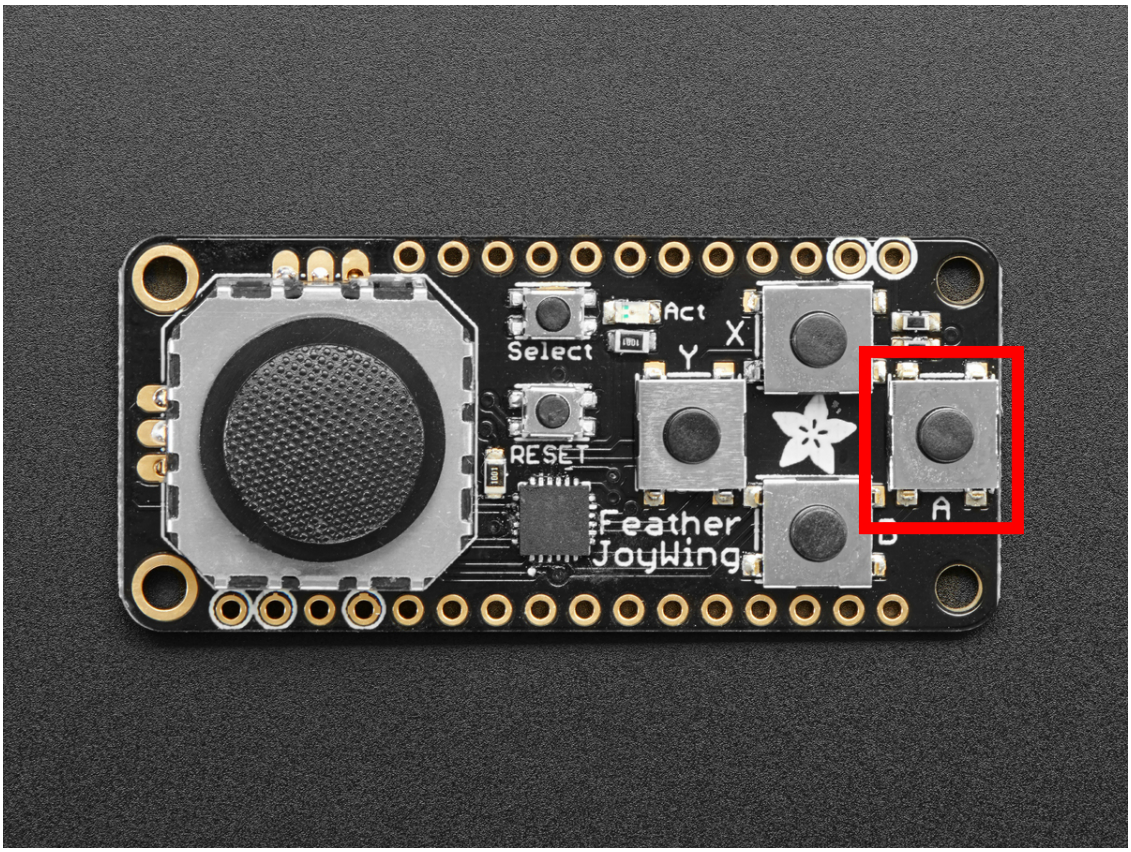
Helper for using the Joy FeatherWing.

- Author(s): Kattni Rembor

class adafruit_featherwing.joy_featherwing.**JoyFeatherWing**
Class representing an Adafruit Joy FeatherWing.

Automatically uses the feather's I2C bus.

button_a
Joy featherwing button A.



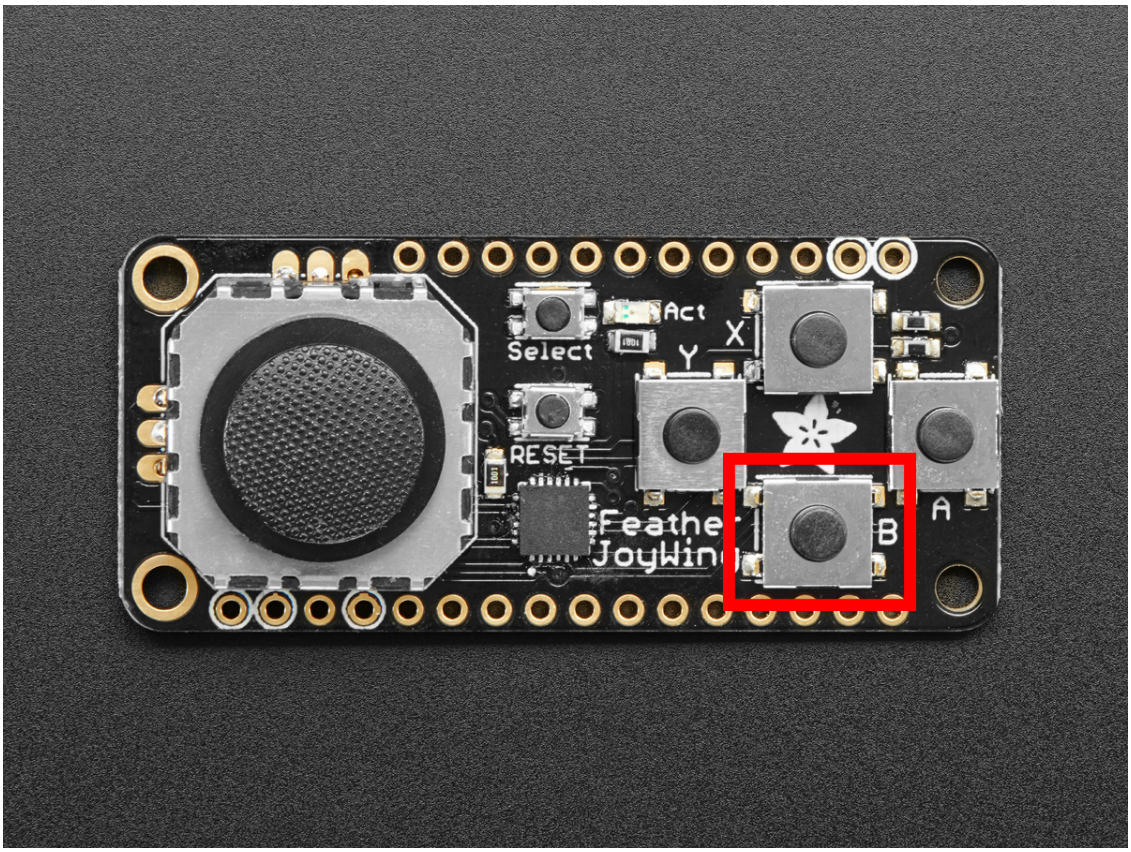
This example prints when button A is pressed.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()

while True:
    if wing.button_a:
    print("Button A pressed!")
```

button_b
Joy featherwing button B.



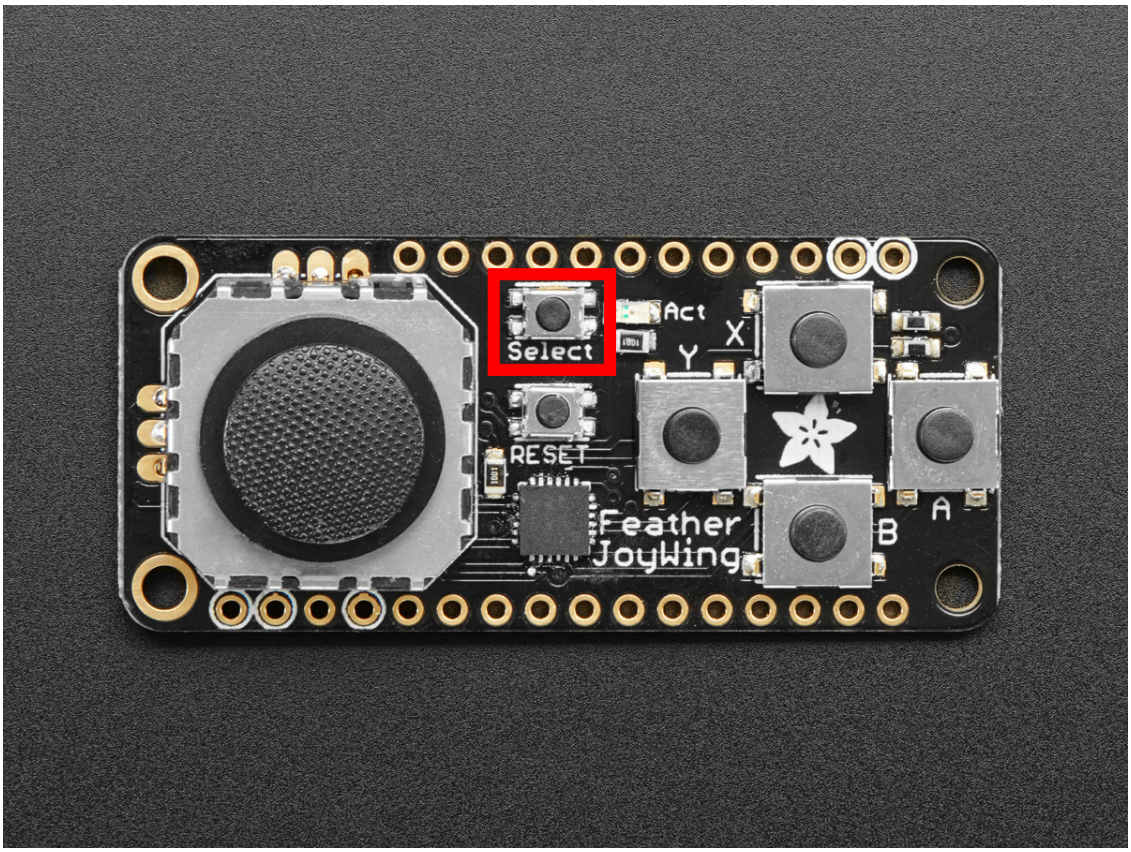
This example prints when button B is pressed.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()

while True:
    if wing.button_b:
    print("Button B pressed!")
```

button_select
Joy featherwing button SELECT.



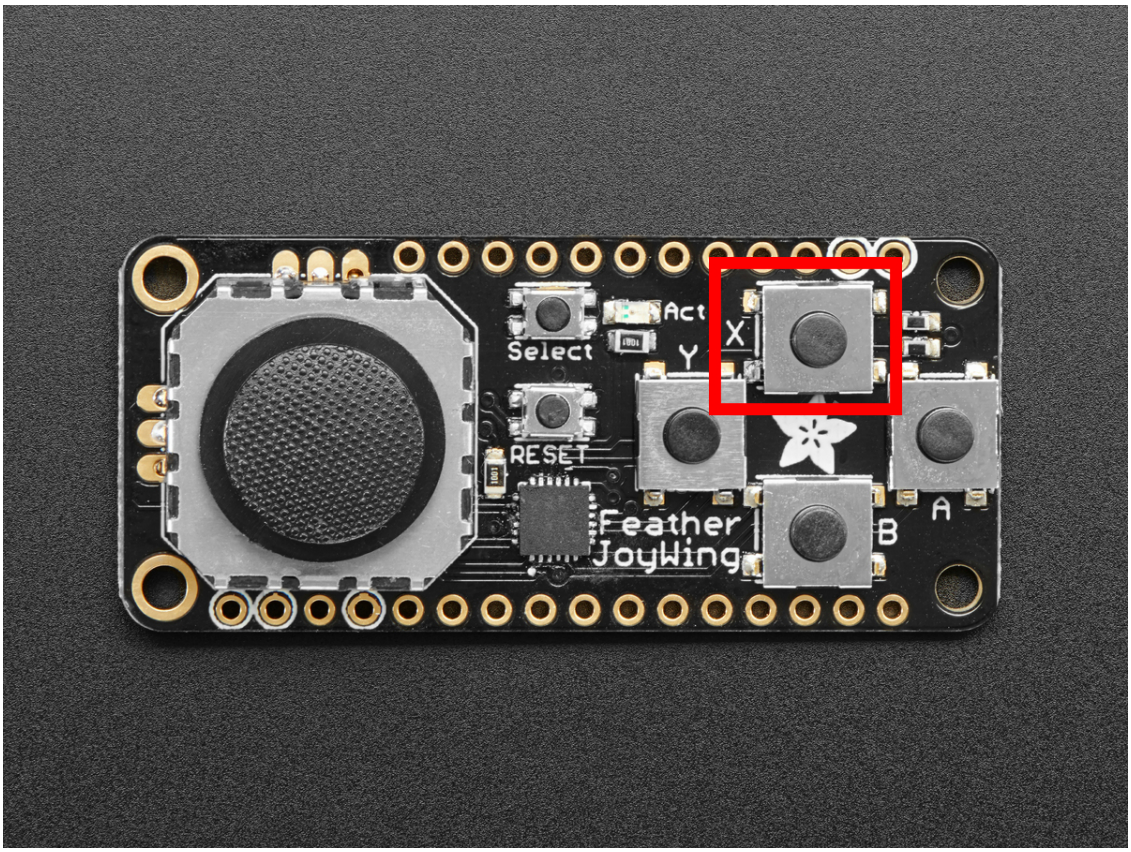
This example prints when button SELECT is pressed.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()

while True:
    if wing.button_select:
    print("Button SELECT pressed!")
```

button_x
Joy featherwing button X.



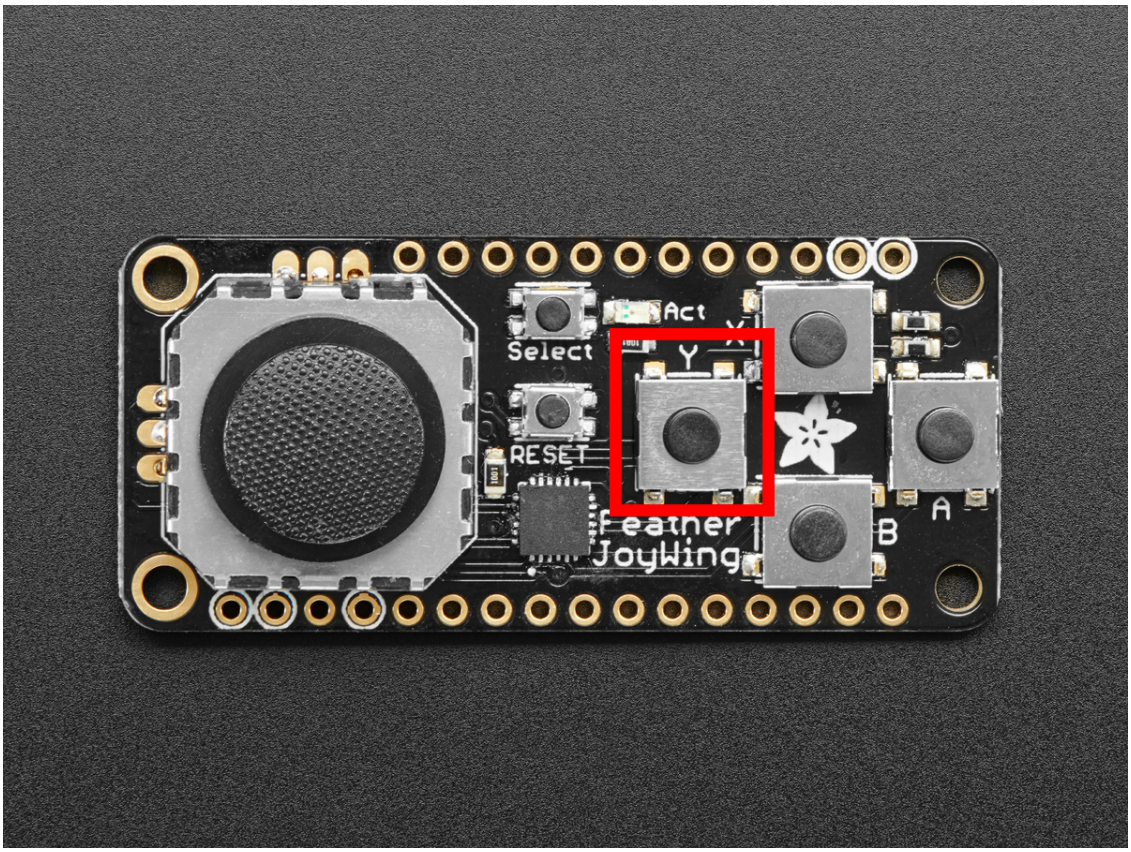
This example prints when button X is pressed.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()

while True:
    if wing.button_x:
    print("Button X pressed!")
```

button_y
Joy featherwing button Y.



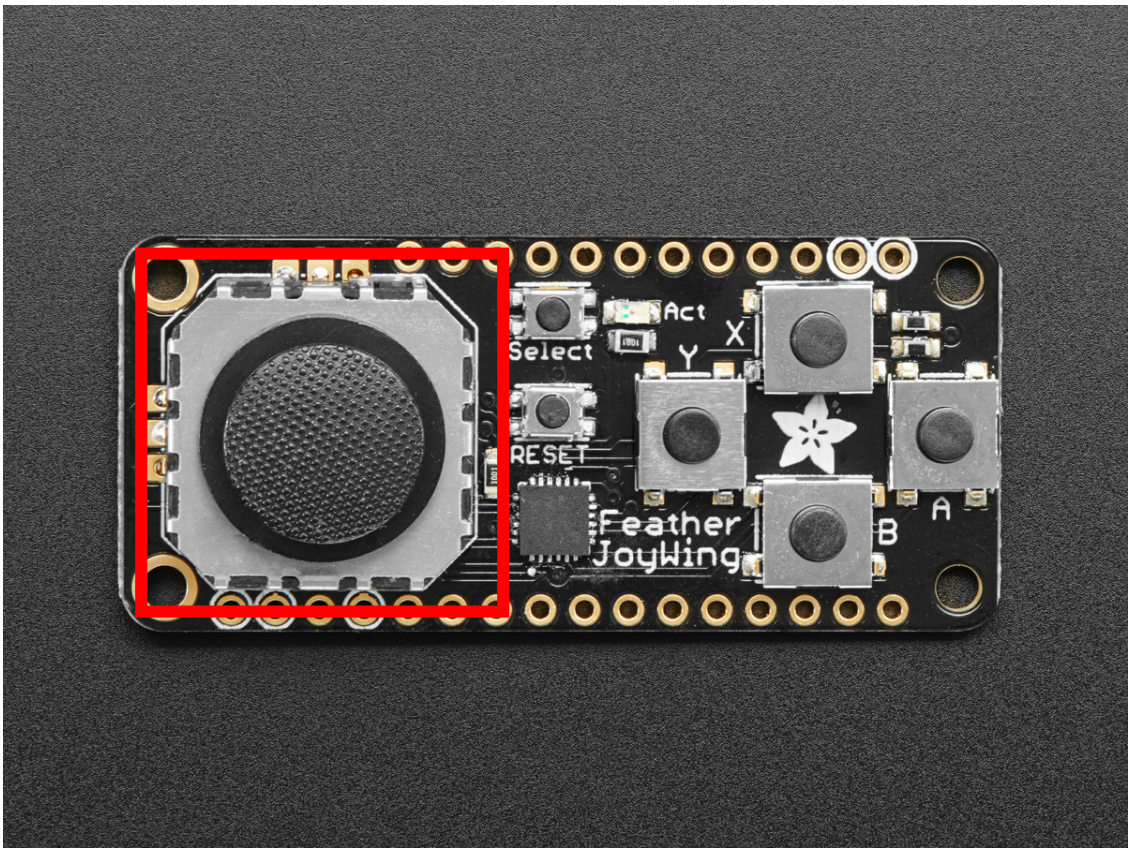
This example prints when button Y is pressed.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()

while True:
    if wing.button_y:
    print("Button Y pressed!")
```

joystick
Joy FeatherWing joystick.



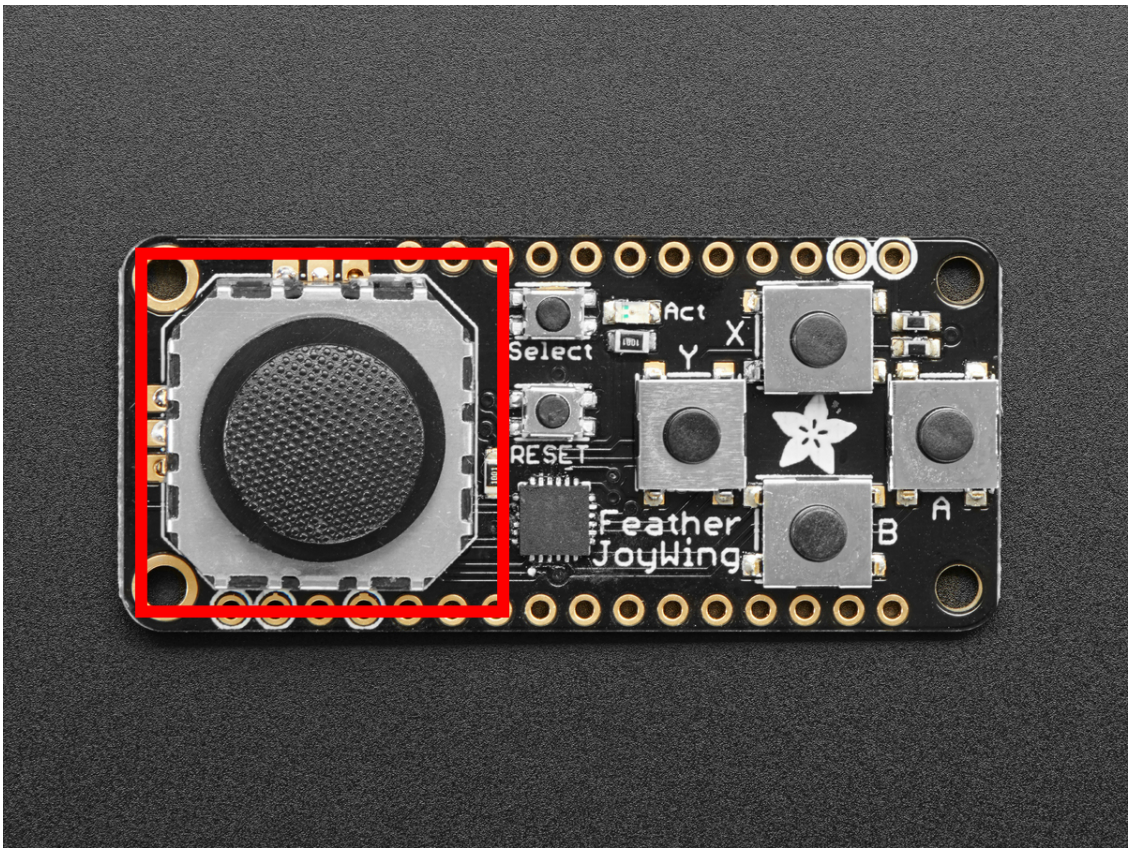
This example zeros the joystick, and prints the coordinates of joystick when it is moved.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()
last_x = 0
last_y = 0
wing.zero_joystick()

while True:
    x, y = wing.joystick
    if (abs(x - last_x) > 3) or (abs(y - last_y) > 3):
        last_x = x
        last_y = y
        print(x, y)
    time.sleep(0.01)
```

joystick_offset
Offset used to correctly report (0, 0) when the joystick is centered.



Provide a tuple of (x, y) to set your joystick center to (0, 0). The offset you provide is subtracted from the current reading. For example, if your joystick reads as (-4, 0), you would enter (-4, 0) as the offset. The code will subtract -4 from -4, and 0 from 0, returning (0, 0).

This example supplies an offset for zeroing, and prints the coordinates of the joystick when it is moved.

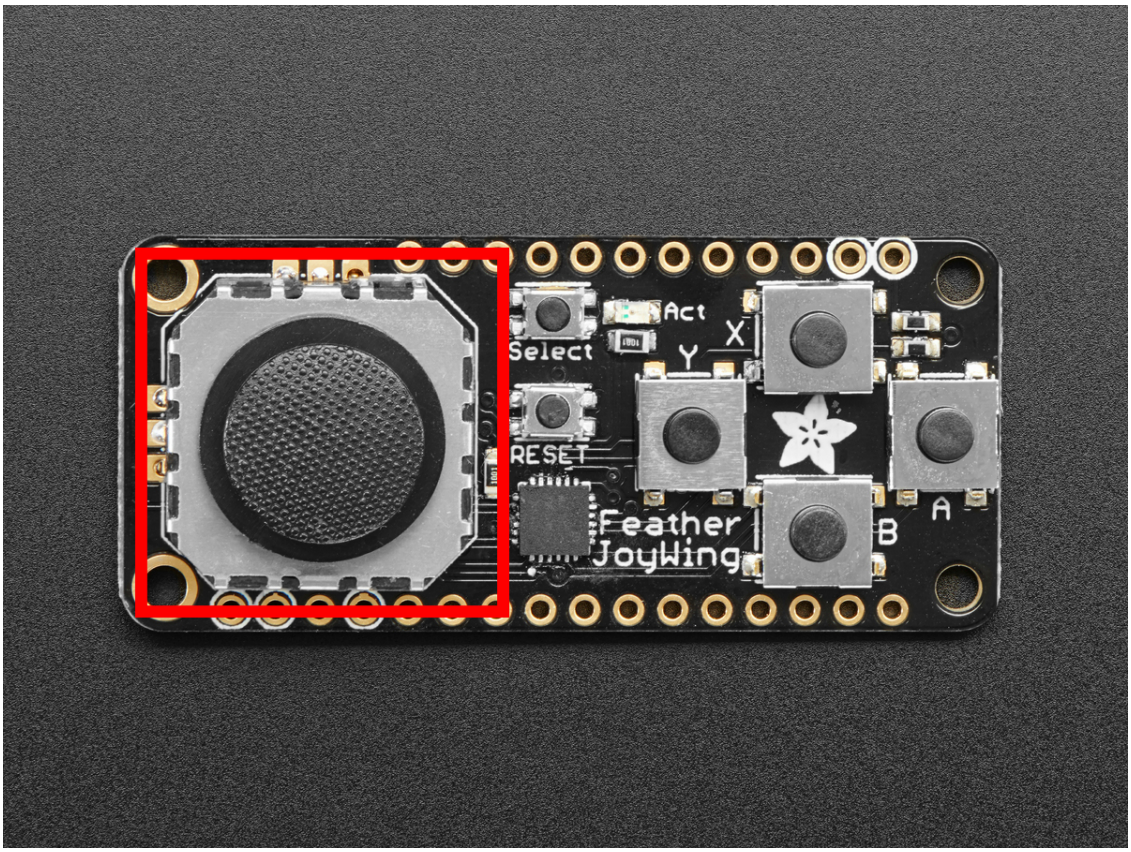
```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()
last_x = 0
last_y = 0

while True:
    wing.joystick_offset = (-4, 0)
    x, y = wing.joystick
    if (abs(x - last_x) > 3) or (abs(y - last_y) > 3):
        last_x = x
        last_y = y
        print(x, y)
    time.sleep(0.01)
```

zero_joystick()

Zeros the joystick by using current reading as (0, 0). Note: You must not be touching the joystick at the time of zeroing for it to be accurate.



This example zeros the joystick, and prints the coordinates of joystick when it is moved.

```
from adafruit_featherwing import joy_featherwing
import time

wing = joy_featherwing.JoyFeatherWing()
last_x = 0
last_y = 0
wing.zero_joystick()

while True:
    x, y = wing.joystick
    if (abs(x - last_x) > 3) or (abs(y - last_y) > 3):
        last_x = x
        last_y = y
        print(x, y)
    time.sleep(0.01)
```

4.4 adafruit_featherwing.alphanum_featherwing

Helper for using the 14-Segment AlphaNumeric FeatherWing.

- Author(s): Melissa LeBlanc-Williams

class adafruit_featherwing.alphanum_featherwing.**AlphaNumFeatherWing**(*address=112*)
Class representing an Adafruit 14-segment AlphaNumeric FeatherWing.

Automatically uses the feather's I2C bus.

blink_rate

Blink Rate returns the current rate that the text blinks. 0 = Off 1-3 = Successively slower blink rates

This example changes the blink rate and prints out the current setting

```
from time import sleep
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()
display.print('Text')

for blink_rate in range(3, -1, -1):
    display.blink_rate = blink_rate
    print("Current Blink Rate is {}".format(display.blink_rate))
    sleep(4)
```

brightness

Brightness returns the current display brightness. 0-15 = Dimmest to Brightest Setting

This example changes the brightness and prints out the current setting

```
from time import sleep
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()
display.print('Text')

for brightness in range(0, 16):
    display.brightness = brightness
    print("Current Brightness is {}".format(display.brightness))
    sleep(0.2)
```

fill(*fill*)

Change all Segments on or off :param bool fill: True turns all segments on, False turns all segments off

This example alternates between all filled and all empty segments.

```
from time import sleep
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()

while True:
    display.fill(True)
    sleep(0.5)
    display.fill(False)
    sleep(0.5)
```

marquee(*text*, *delay=0.25*, *loop=True*)

Automatically scroll the text at the specified delay between characters

Parameters

- **text** (*str*) – The text to display
- **delay** (*float*) – (optional) The delay in seconds to pause before scrolling to the next character (default=0.25)
- **loop** (*bool*) – (optional) Whether to endlessly loop the text (default=True)

```
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()
display.marquee('This is some really long text  ')
```

print(*value*)

Print a number or text to the display

Parameters **value** (*str or int or float*) – The text or number to display

```
from adafruit_featherwing import alphanum_featherwing

display = alphanum_featherwing.AlphaNumFeatherWing()
display.print(1234)
```

CHAPTER 5

Indices and tables

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