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# **Adafruit LSM9DS1 Library Documentation**

***Release 1.0***

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CircuitPython module for the LSM9DS1 accelerometer, magnetometer, gyroscope.



# CHAPTER 1

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## Dependencies

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This driver depends on:

- [Adafruit CircuitPython](#)
- [Bus Device](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).





## CHAPTER 2

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### Usage Example

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See `examples/lsm9ds1_simpletest.py` for a demo of the usage.



## CHAPTER 3

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### Contributing

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Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.



## CHAPTER 4

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### Building locally

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To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-lsm9ds1 --
↳library_location .
```

### 4.1 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the `index.html` in your browser to view them. It will also (due to `-W`) error out on any warning like Travis will. This is a good way to locally verify it will pass.



## 5.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/lsm9ds1\_simpletest.py

```

1  # Simple demo of the LSM9DS1 accelerometer, magnetometer, gyroscope.
2  # Will print the acceleration, magnetometer, and gyroscope values every second.
3  import time
4  import board
5  import busio
6  import adafruit_lsm9ds1
7
8  # I2C connection:
9  i2c = busio.I2C(board.SCL, board.SDA)
10 sensor = adafruit_lsm9ds1.LSM9DS1_I2C(i2c)
11
12 # Main loop will read the acceleration, magnetometer, gyroscope, Temperature
13 # values every second and print them out.
14 while True:
15     # Read acceleration, magnetometer, gyroscope, temperature.
16     accel_x, accel_y, accel_z = sensor.acceleration
17     mag_x, mag_y, mag_z = sensor.magnetic
18     gyro_x, gyro_y, gyro_z = sensor.gyro
19     temp = sensor.temperature
20     # Print values.
21     print('Acceleration (m/s^2): ({0:0.3f},{1:0.3f},{2:0.3f})'.format(accel_x, accel_
↪y, accel_z))
22     print('Magnetometer (gauss): ({0:0.3f},{1:0.3f},{2:0.3f})'.format(mag_x, mag_y,
↪mag_z))
23     print('Gyroscope (degrees/sec): ({0:0.3f},{1:0.3f},{2:0.3f})'.format(gyro_x, gyro_
↪y, gyro_z))
24     print('Temperature: {0:0.3f}C'.format(temp))

```

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```
25     # Delay for a second.  
26     time.sleep(1.0)
```

## 5.2 adafruit\_lsm9ds1

CircuitPython module for the LSM9DS1 accelerometer, magnetometer, gyroscope. Based on the driver from: [https://github.com/adafruit/Adafruit\\_LSM9DS1](https://github.com/adafruit/Adafruit_LSM9DS1)

See examples/simpletest.py for a demo of the usage.

- Author(s): Tony DiCola

### 5.2.1 Implementation Notes

#### Hardware:

- Adafruit 9-DOF Accel/Mag/Gyro+Temp Breakout Board - LSM9DS1 (Product ID: 3387)

#### Software and Dependencies:

- Adafruit CircuitPython firmware for the ESP8622 and M0-based boards: <https://github.com/adafruit/circuitpython/releases>
- Adafruit's Bus Device library: [https://github.com/adafruit/Adafruit\\_CircuitPython\\_BusDevice](https://github.com/adafruit/Adafruit_CircuitPython_BusDevice)

**class** `adafruit_lsm9ds1.LSM9DS1`

Driver for the LSM9DS1 accelerometer, magnetometer, gyroscope.

#### **accel\_range**

The accelerometer range. Must be a value of: - ACCELRange\_2G - ACCELRange\_4G - ACCELRange\_8G - ACCELRange\_16G

#### **acceleration**

The accelerometer X, Y, Z axis values as a 3-tuple of m/s<sup>2</sup> values.

#### **gyro**

The gyroscope X, Y, Z axis values as a 3-tuple of degrees/second values.

#### **gyro\_scale**

The gyroscope scale. Must be a value of: - GYROScale\_245DPS - GYROScale\_500DPS - GYROScale\_2000DPS

#### **mag\_gain**

The magnetometer gain. Must be a value of: - MAGGain\_4GAUSS - MAGGain\_8GAUSS - MAGGain\_12GAUSS - MAGGain\_16GAUSS

#### **magnetic**

The magnetometer X, Y, Z axis values as a 3-tuple of gauss values.

#### **read\_accel\_raw()**

Read the raw accelerometer sensor values and return it as a 3-tuple of X, Y, Z axis values that are 16-bit unsigned values. If you want the acceleration in nice units you probably want to use the accelerometer property!

#### **read\_gyro\_raw()**

Read the raw gyroscope sensor values and return it as a 3-tuple of X, Y, Z axis values that are 16-bit unsigned values. If you want the gyroscope in nice units you probably want to use the gyroscope property!



**read\_mag\_raw()**

Read the raw magnetometer sensor values and return it as a 3-tuple of X, Y, Z axis values that are 16-bit unsigned values. If you want the magnetometer in nice units you probably want to use the magnetometer property!

**read\_temp\_raw()**

Read the raw temperature sensor value and return it as a 12-bit signed value. If you want the temperature in nice units you probably want to use the temperature property!

**temperature**

The temperature of the sensor in degrees Celsius.

**class** adafruit\_lsm9ds1.**LSM9DS1\_I2C** (*i2c*)

Driver for the LSM9DS1 connect over I2C.

**class** adafruit\_lsm9ds1.**LSM9DS1\_SPI** (*spi, xgcs, mcs*)

Driver for the LSM9DS1 connect over SPI.



## CHAPTER 6

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